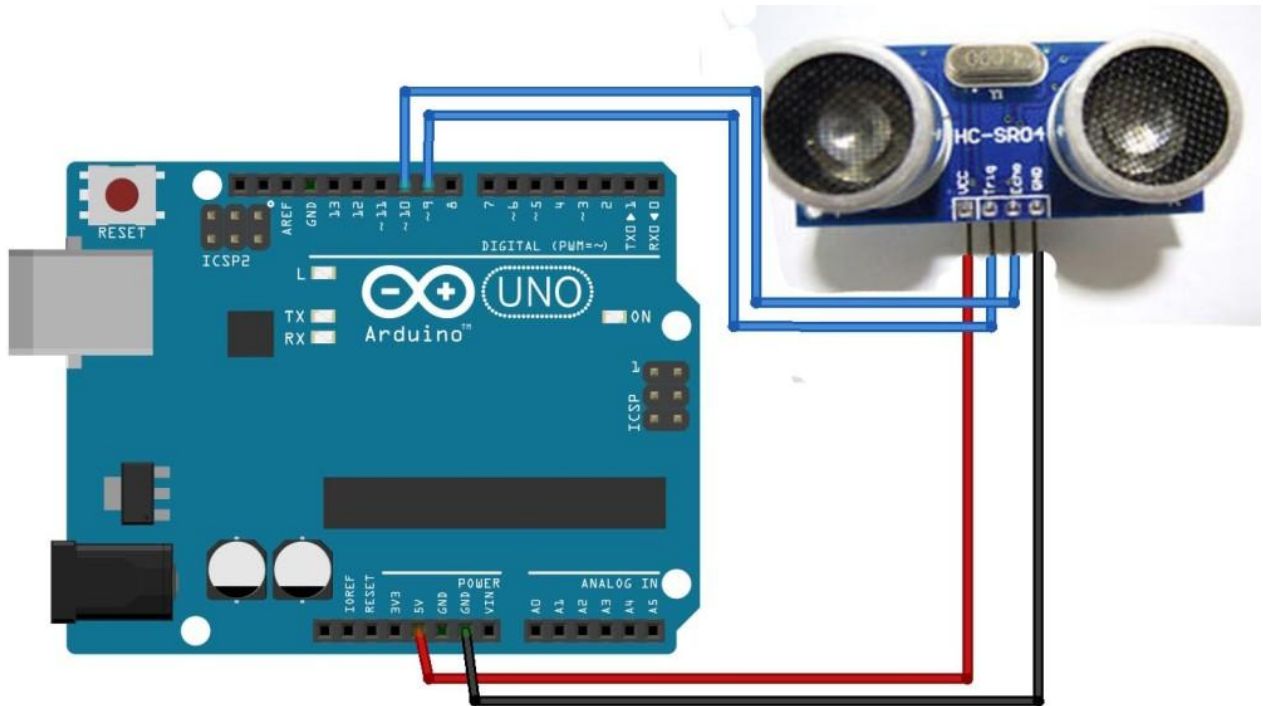


# SENSORE AD ULTRASUONI HC-SR04 – ARDUINO

Riferimento:

<http://www.giuseppecaccavale.it/arduino/sensore-ad-ultrasuoni-hc-sr04-arduino/>



QUI una libreria in grado di migliorare la lettura e la sensibilità di questo sensore:

<https://www.dropbox.com/s/s47utngoflgahjn/NewPing.zip?dl=0>

Ricordate di copiare la libreria in `\Documents\Arduino\libraries\...`

oppure in

`C:\ProgramFiles\Arduino\libraries\...`

Posto qui un esempio, i collegamenti sono uguali a quelli dell'esempio con monitor seriale

```
1 //HC RS04 Sensore ultrasuoni
2
3 #include <NewPing.h>
4 #define TRIGGER_PIN 9 // Arduino pin tied to trigger pin on the ultrasonic sensor.
5 #define ECHO_PIN 10 // Arduino pin tied to echo pin on the ultrasonic sensor.
6 #define MAX_DISTANCE 400 // Maximum distance we want to ping for (in centimeters). Maximum sensor
7 distance is rated at 400-500cm.
8
9 NewPing sonar(TRIGGER_PIN, ECHO_PIN, MAX_DISTANCE);
10
11 int SetDistance = 0;
12 int ValueDist = 0;
```

```
13
14 void setup() {
15   Serial.begin(115200);
16 }
17
18 void loop() {
19   delay(2000); // Wait 50ms between pings (about 20 pings/sec). 29ms should be the shortest delay between pings.
20   unsigned int uS = sonar.ping(); // Send ping, get ping time in microseconds (uS).
21   ValueDist = uS * 10 / US_ROUNDTRIP_CM;
22
23   Serial.print("Ping: ");
24   Serial.print(ValueDist); // Convert ping time to distance in cm and print result (0 = outside set distance range)
25   Serial.println("cm");
26
27 }
```